

Co-simulation of Cyber-Physical Systems using HLA

IEEE CCWC 2017 conference, January 9, 2017

Thomas Nägele

t.nagele@cs.ru.nl



iCIS | Software Science
Radboud University



Contents

Introduction

Software modelling

Connecting models using HLA

Example: RoomThermostat

Conclusion

Questions

iCIS | Software Science
Radboud University



Introduction

Cyber-physical systems (CPSs)



CPS development

- Development of CPSs is a multi-disciplinary process
 - Mechanics, electronics, software, ...



Introduction

Long-term goal

Develop a model-based methodology to improve the multi-disciplinary development process of CPSs.

- Virtual prototyping using models of both hardware and software
 - Current models often implicitly contain software components
 - Clear separation of software and hardware layers
- Implementing software alongside the design of the hardware
 - Modular co-simulation

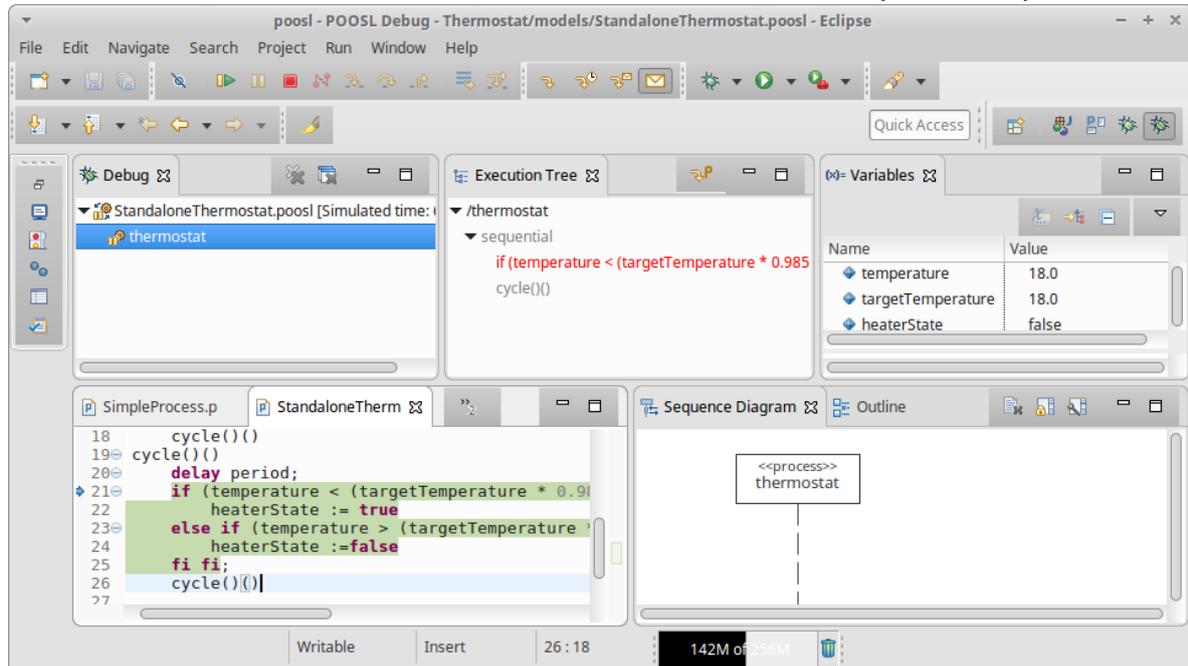
Current goals

- The use of existing standards for our co-simulation
- Separation of software models



Software modelling

Parallel Object-Oriented Specification Language (POOSL)



Connecting models using HLA

Constructing a co-simulation

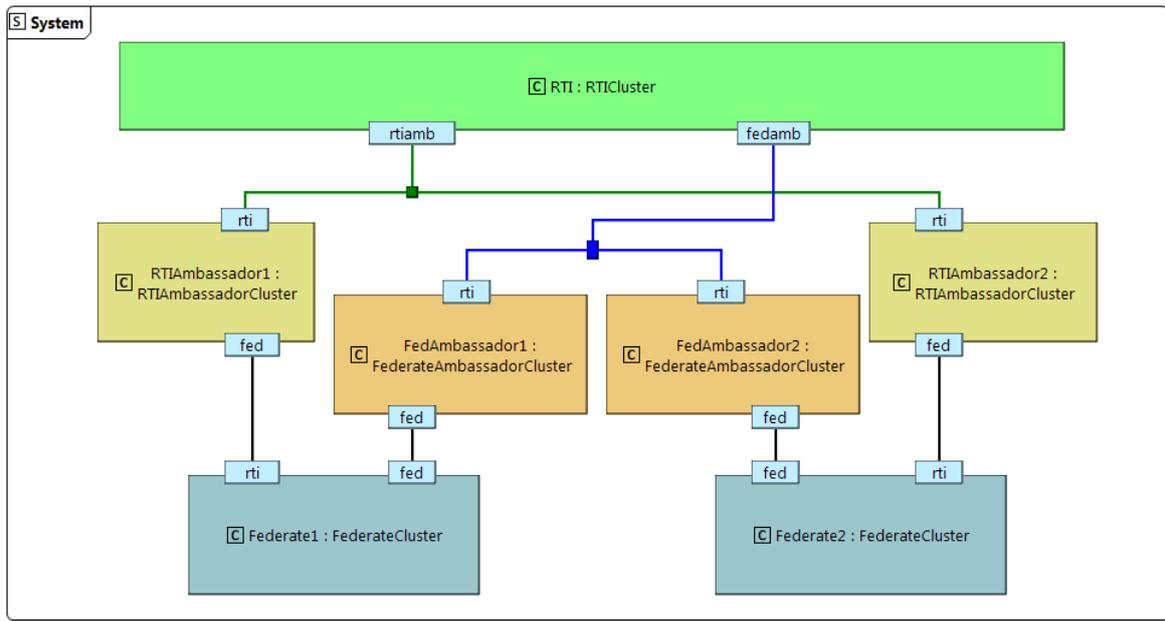
- Different types of models to be co-simulated
 - Discrete-time models of software
 - Continuous-time models of hardware
- What should be synchronised across simulations?
 - Time, attributes, interactions, ...

High-Level Architecture (HLA)

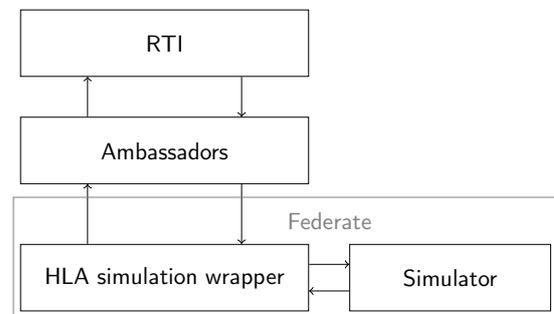
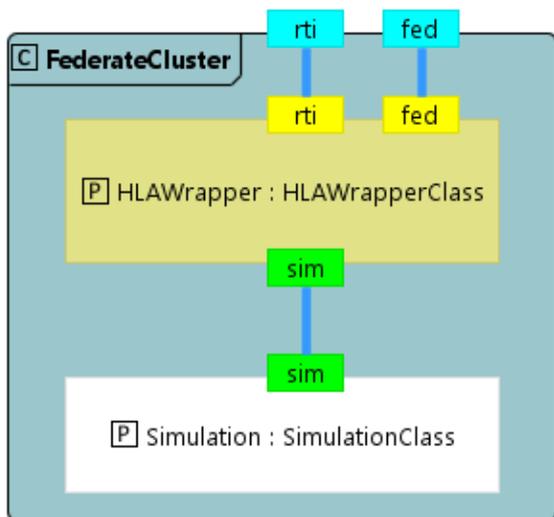
- Standardised (IEEE Standard 1516) interface
 - Public and commercial implementations
 - Various modelling and simulation tools
- Connecting simulations from different tools
- Highly configurable
- Distributed co-simulation



Connecting models using HLA

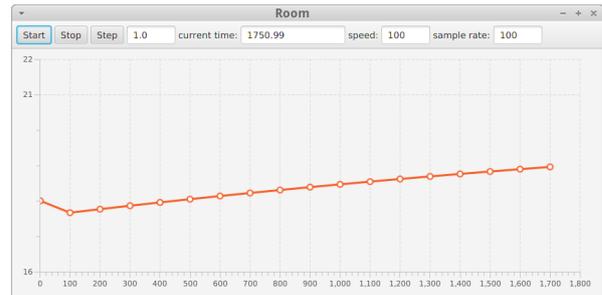
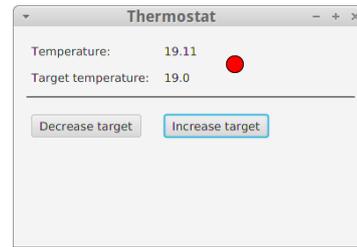


Connecting models using HLA



Example: RoomThermostat

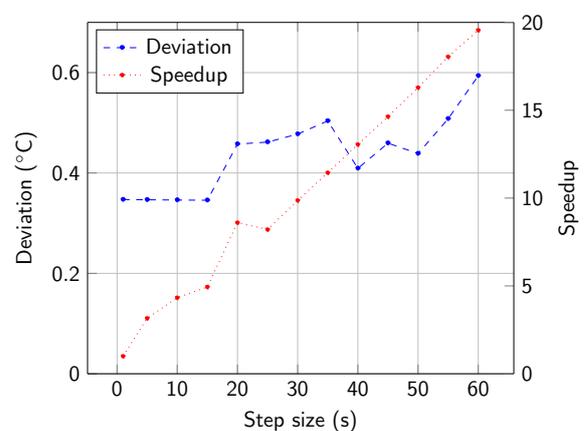
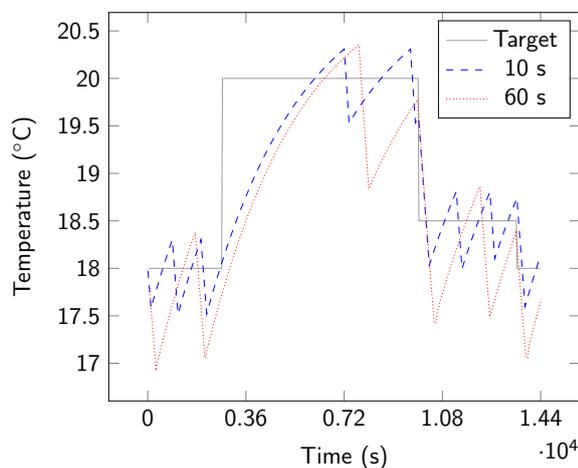
- Proof of concept
- Open-source RTI: PoRTIco
- Room environment model
 - Continuous time
 - Created in OpenModelica
 - Exported to FMU
- Thermostat controller model
 - Discrete time model
 - Created with POOSL
 - Simulated by Rotalumis
- Two graphical user interfaces
 - Time control
 - User input



Example: RoomThermostat

Observations

- How does step size of the continuous model affect the simulation?
 - Accuracy
 - Performance



Conclusion

Findings

- FMI supported by many different tools
- HLA standard is very useful for modular setups
- Co-simulation to be used as virtual prototype
 - Allows analysis on system modifications or extensions
 - ▶ Alternative exploration
 - Allows testing without hardware
 - ▶ Fault injection

Future work

- Apply the approach to an industrial application
- Investigate scalability of the method
- Experiment with distributed simulations
- Code generation from a Domain Specific Language



Questions

Thank you for your attention! Are there any questions?

